

FIG. 1

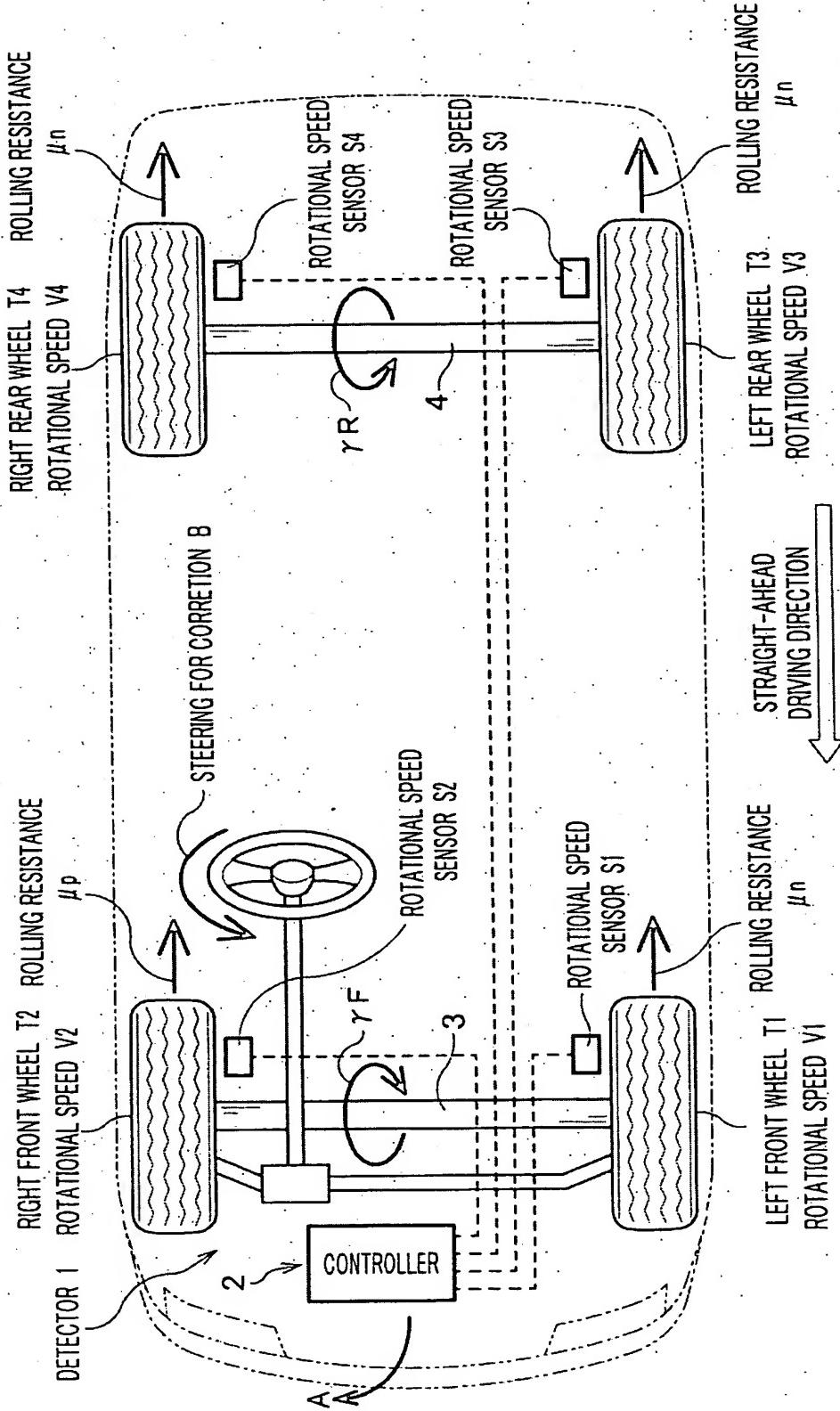


FIG.2

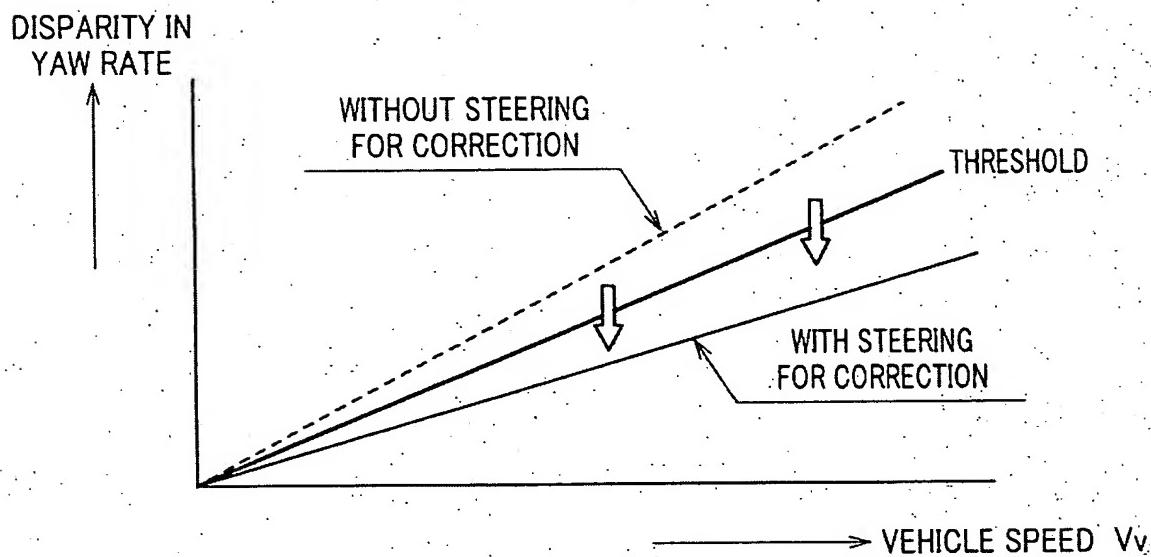


FIG.3

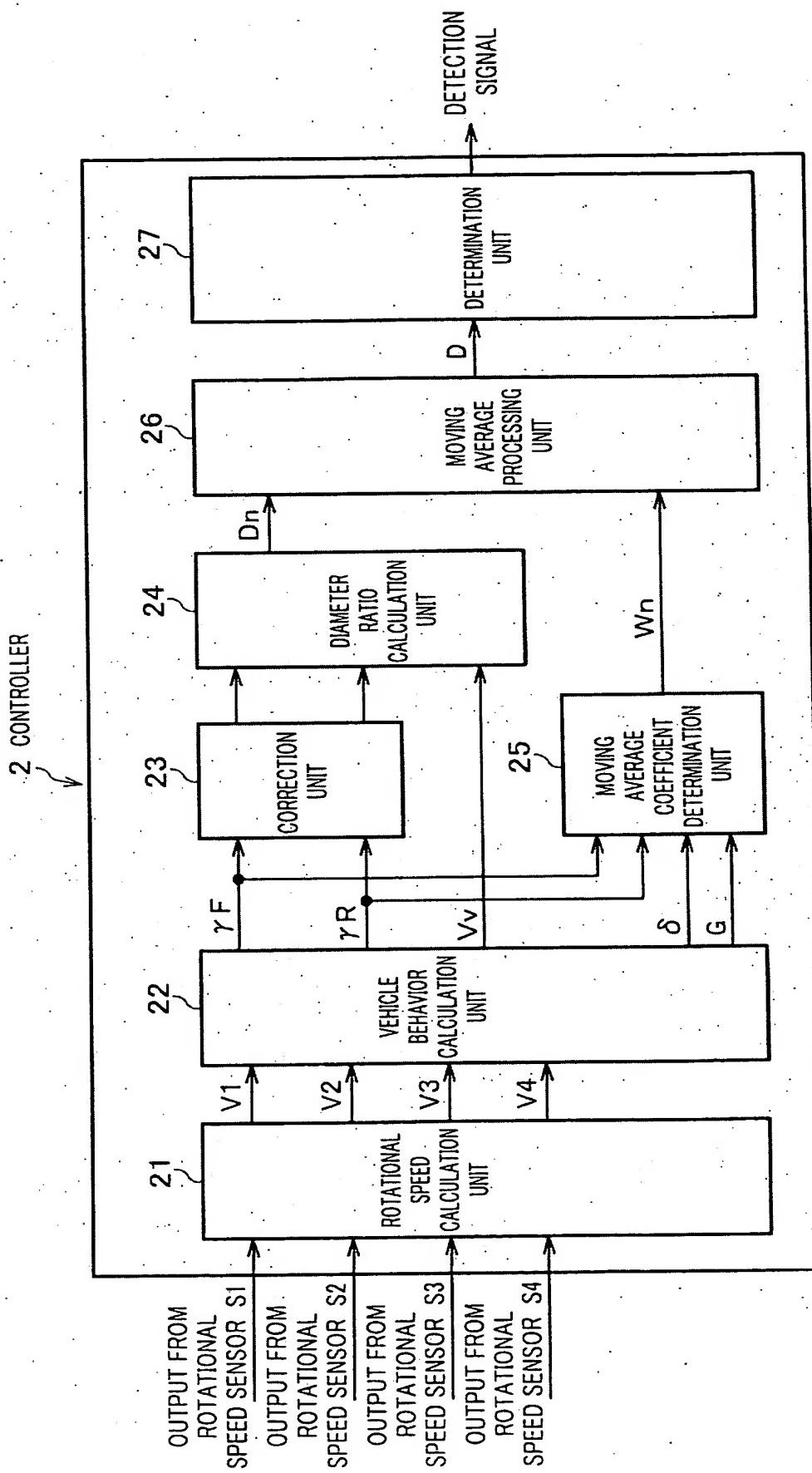


FIG.4

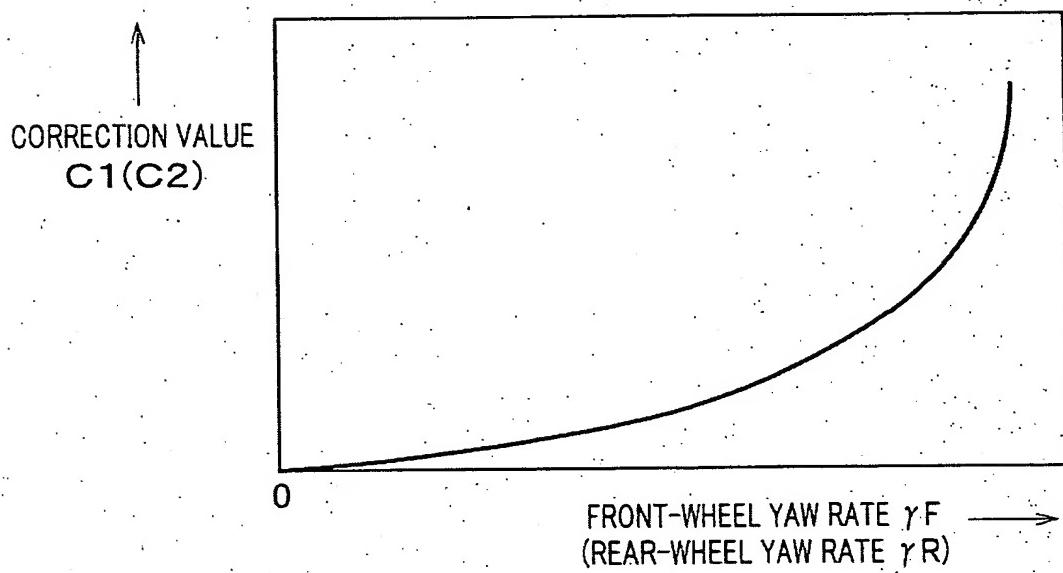
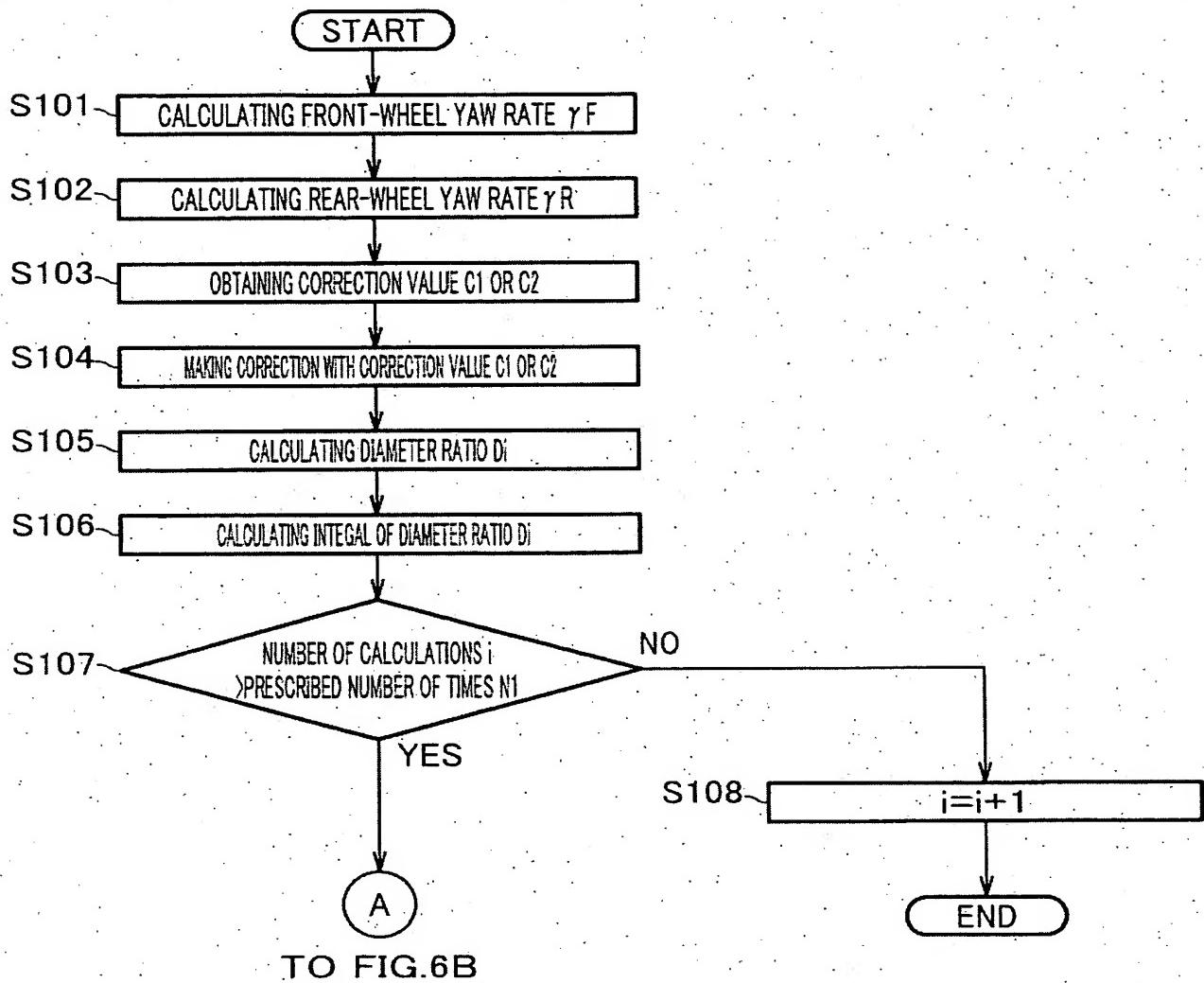


FIG.5

		FRONT-WHEEL YAW RATE $\gamma_F$	REAR-WHEEL YAW RATE $\gamma_R$
MAP RETRIEVAL WITH FRONT-WHEEL YAW RATE $\gamma_F$	a1	CORRECTION TO FRONT WHEELS T1,T2	$\gamma_F = \gamma_F \times C_1$
	b1	CORRECTION TO REAR WHEELS T3,T4	$\gamma_R = \gamma_R / C_1$
MAP RETRIEVAL WITH REAR-WHEEL YAW RATE $\gamma_R$	c1	CORRECTION TO FRONT WHEELS T1,T2	$\gamma_F = \gamma_F / C_2$
	d1	CORRECTION TO REAR WHEELS T3,T4	$\gamma_R = \gamma_R \times C_2$

FIG.6A



TO FIG.6B

FIG.6B

FROM FIG.6A

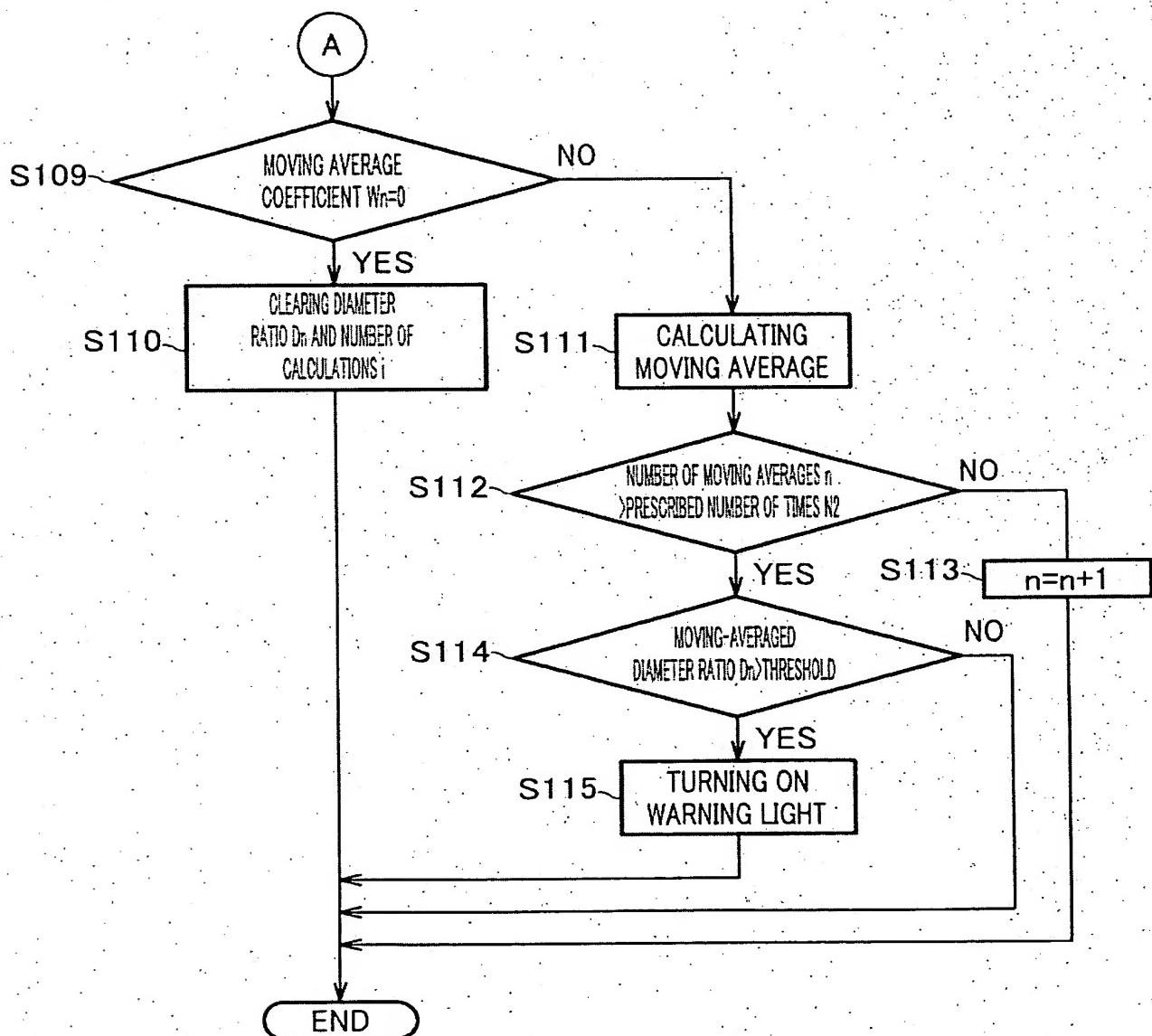


FIG. 7

		FRONT-WHEEL YAW RATE $\gamma_F$	REAR-WHEEL YAW RATE $\gamma_R$
CALCULATION OF FRONT-WHEEL YAW RATE DEVIATION $\gamma_{P1}$	a2	CORRECTION TO FRONT WHEELS T1,T2	$\gamma_F = \gamma_F - \gamma_{P1}$
	b2	CORRECTION TO REAR WHEELS T3,T4	$\gamma_R = \gamma_R + \gamma_{P1}$
CALCULATION OF REAR-WHEEL YAW RATE DEVIATION $\gamma_{P2}$	c2	CORRECTION TO FRONT WHEELS T1,T2	$\gamma_F = \gamma_F + \gamma_{P2}$
	d2	CORRECTION TO REAR WHEELS T3,T4	$\gamma_R = \gamma_R - \gamma_{P2}$